Near-equivalence in Forecasting Accuracy of Linear Dimension Reduction Methods in Large Macro-Panels

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Near-equivalence in Forecasting Accuracy of Linear Dimension Reduction Metho /38

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Overview of Empirical Results



The Empirical Forecasting Exercise

- McCracken and Ng (2015) created the FRED-MD macro-panel:
 - 123 monthly macro variables.
 - From January 1960 to 2015, balanced panel of 110 predictors with approx. 660 data.
- Focus on: CPI inflation, non-farm payrolls, unemployment rate, labor force participation, average hourly earnings in goods-producing industries, industrial production, real personal consumption expenditures and real personal income.
- Use popular statistical learning methods OLS, PCR, RIDGE, PLS and SIR (Sliced Inverse Regression).
 - Out-of-sample forecasts using recursive window at horizons h = 1, 3, 6, 12.
 - Compare results in classic horse-race against AR(4).

 Dynamic Factor Models (DFMs) are the mainstream methodology in Econometrics for both measuring comovement and forecasting time series.

• The modeling comprises of two unconnected steps: The factors that replace \mathbf{x}_t are ordered according to how much variance in \mathbf{X} they explain; i.e., in relevance to \mathbf{X} and not to Y.

Table: Recursive Out-of-Sample Window from 1992 to 2007, MSFE Relative to AR4 $% \left({{\rm AR4}} \right) = {\rm AR4}$

	h=1		h=3		h=6		h=12	
Target	Estimator	MSFE	Estimator	MSFE	Estimator	MSFE	Estimator	MSFE
INDPRO	RIDGE ^b -119	0.87	RIDGE ^b -141	0.95	R70SIRb ^{c, d} -2	0.95	R8SIRb ^{c, d} -2	0.9
PAYEMS	R30SIRb ^{c,d} -1	0.96	R30SIRb ^{c,d} -1	0.94	R30SIRb ^{c,d} -2	0.87	R30SIRb ^{c, d} -2	0.82
UNRATE	PC-1	0.93	PLS-1	0.76	RIDGE ^b -0.4	0.76	RIDGE ^b -0.3	0.78
CLF16O	RIDGE ^b -141	0.94	PC-16	0.87	PC-23	0.81	PC-16	0.74
CPIAUC	PC.BS ^h -8.7	0.89	SIRb ^d -2	0.94	PC.ON ^f -1.2	0.97	R8SIRb ^{c, d} -2	0.95
CES060	PLS-1	0.99	PLS-1	1	R8SIRb ^{c,d} -1	0.97	AR4	1
DPCER	AR4	1	AR4	1	AR4	1	AR4	1
RPI	R8SIRb ^{c,d} -1	0.93	R8SIRb ^{c, d} -1	0.88	R8SIRb ^{c,d} -1	0.88	RFSIRb ^{c, d} -1	0.83

Table: Recursive Out-of-Sample Window from 2010 to 2016, MSFE Relative to AR4 $% \left({{\rm AR4}} \right) = {\rm AR4}$

	h=1		h=3		h=6		h=12	
Target	Estimator	MSFE	Estimator	MSFE	Estimator	MSFE	Estimator	MSFE
INDPRO	RIDGE ^b -949	0.96	RIDGE ^b -949	0.93	RIDGE ^b -3532	0.94	R30SIRb ^{c,d} -3	0.74
PAYEMS	RIDGE ^b -141	0.74	RIDGE ^b -141	0.56	RIDGE ^b -288	0.5	RIDGE ^b -288	0.44
UNRATE	PCF.BS ⁱ -11	0.85	PLS-4	0.64	SIRa ^d -7	0.55	PC.BS ^h -1	0.38
CLF16O	PC-7	0.78	PCF.BS ⁱ -11	0.52	RIDGE ^b -0.6	0.39	PLS-5	0.33
CPIAUC	PC.BS ^h -1	0.96	SIRb ^d -1.3	0.9	R70SIRb ^{c,d} -3	0.94	PC-5	0.87
CES060	SIRa ^d -7	0.94	SIRb ^d -1	0.99	R8SIRb ^{c,d} -3.5	0.94	R8SIRa ^{c, d} -2	0.87
DPCER	PC-5	0.87	PC-5	0.7	PC-5	0.48	PC-17	0.44
RPI	R8SIRa ^{c, d} -1	0.91	RFSIRa ^{c, d} -1.6	0.79	PLS-8	0.78	PLS-20	0.64

Table: Recursive Out-of-Sample Window from 1992 to 2016, MSFE Relative to AR4 $% \left({{\rm AR4}} \right) = {\rm AR4}$

	h=1		h=3		h=6		h=12	
Target	Estimator	MSFE	Estimator	MSFE	Estimator	MSFE	Estimator	MSFE
INDPRO	PC-15	0.95	PC-15	0.94	SIRb ^d -1.4	0.96	R70SIRb ^{c, d} -3	0.94
PAYEMS	R8SIRb ^{c,d} -1	0.88	R8SIRb ^{c, d} -1	0.82	R8SIRb ^{c,d} -1	0.89	R30SIRb ^{c, d} -2	0.9
UNRATE	PC-15	0.9	PC-3	0.74	PC-3	0.73	PC-3	0.76
CLF16O	PC-11	0.88	PC-17	0.69	PC-20	0.56	PC-17	0.41
CPIAUC	PLS-3	0.9	RFSIRb ^{c, d} -5.1	0.91	SIRb ^d -4	0.97	R8SIRb ^{c, d} -1	0.99
CES060	AR4	1	SIRb ^d -1	0.99	R8SIRb ^{c, d} -1	0.94	PC-1	0.92
DPCER	PC.ON ^f -1.5	0.93	PC-1	0.92	RFSIRb ^{c,d} -1	0.94	R8SIRb ^{c, d} -1	0.94
RPI	PLS-1	0.91	PLS-1	0.85	PLS-1	0.82	PLS-1	0.8

^bThe number after RIDGE Comp. is value of regularization param.

^cR#SIR is regularized SIR. # refers to number of leading PCs used for regularization. ^dIn type–a SIR target is y_{t+h} . In type–b SIR target is y_t .

^eRFSIR is regularized SIR on most frequently selected PCs by out-of-sample best subset selection.

^fPC.ON is PCR in which number of components is chosen using Onatski criterion. ^gPC.ICP1 is PCR in which number of components is chosen using Bai-Ng criterion. ^hPC.BS is PCR in which number of components is chosen by best subset selection. ⁱPCF.BS is PCR in which number of components is chosen by best subset selection applied on most frequently chosen PCs in out-of-sample.

Near-Equivalence in Forecast Accuracy

- Great variability of best estimator depending on (target-sample-horizon) triplet.
- Sometimes beating AR(4) remains a challenging task.
- SIR-type estimators do fairly well, PLS is the estimator represented the least in the tables.
- Competitive edge of SIR is its parsimony: attains practically the same forecasting accuracy using one or two linear combinations of the predictors
- No Clear Winner result ubiquitous in macro-forecasting literature.
- Can we explain the results?

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Selection of PCs Using Different Criteria

Figure: Av. Num. of PC Comp. Selected by BSS versus ICps Over 1992-2010.



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MSFE As A Function of Number of Components



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Common Forecasting Framework



Forecasting with Many Predictors

- Forecasting target variable y with a large set of predictors $\mathbf{x} \in \mathbb{R}^{p}$.
- Starting forecasting model includes all x predictors:

$$y_{t+h} = \alpha_0 + \alpha'_1 \mathbf{x}_t + \alpha'_2 \mathbf{w}_t + \varepsilon_{t+h}$$

- \mathbf{w}_t may contain additional regressors such as lags of y_t
- $E(\varepsilon_{t+h}) = 0$
- $\alpha_1' \mathbf{x}_t$ and $\alpha_2' \mathbf{w}_t$ are uncorrelated with ε_{t+h}
- Naturally conducive to OLS to estimate α₁ and α₂ and the feasible forecast is

$$\widehat{y}_{t+h} = \widehat{\alpha}_0 + \widehat{\alpha}'_1 \mathbf{x}_t + \widehat{\alpha}'_2 \mathbf{w}_t$$

- OLS estimation can be problematic when p is large relative to T, or variables in x_t are nearly collinear, as in macro forecasting ⇒ dimension reduction.
- Dimension reduction methods in regression fall into two categories:
 - Variable Selection: subset of the original predictors is selected for modeling the response (e.g. Stepwise Regression, All Subset Selection, LASSO) => Some predictors are discarded
 - ▶ Feature Extraction: linear combinations of the regressors replace the original regressors, therefore reduction of p happens prior to model fitting (e.g. PCR) ⇒ All predictors are retained.

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Forecasting with Extracted Linear Features

Assuming

$$y_{t+h} = \boldsymbol{\alpha}' \mathbf{x}_t + \varepsilon_{t+h}$$

Forecasting with extracted features is implemented in two steps:

(i) Extract reduced features

$$\mathbf{f}_t = \boldsymbol{\beta}' \mathbf{x}_t$$

(ii) Fit the *reduced* model

$$y_{t+h} = \boldsymbol{\gamma}' \mathbf{f}_t + \varepsilon_{t+h}$$
$$= (\boldsymbol{\beta} \boldsymbol{\gamma})' \mathbf{x}_t + \varepsilon_{t+h}$$

Justifying Reduced Model

Proposition

Suppose **x** is a random p-vector with finite first two moments. Assume $y = \alpha' \mathbf{x} + \varepsilon$, with $\mathsf{E}(\varepsilon) = 0$ and $\mathsf{Cov}(\varepsilon, \mathbf{x}) = 0$ where $\alpha \in \mathbb{R}^p$ is unknown, and $\mathbf{f} = \beta' \mathbf{x}$, where the $p \times r$ matrix β is such that (i) for each α , $\mathsf{E}(\alpha' \mathbf{x} | \beta' \mathbf{x} = \mathbf{f})$ is linear in $\mathbf{f} \in \mathbb{R}^r$ (LC); (ii) for each α , $\mathsf{Var}(\alpha' \mathbf{x} | \beta' \mathbf{x} = \mathbf{f})$ is constant in $\mathbf{f} \in \mathbb{R}^r$ (CVC).

Then, y can be decomposed into the sum of a linear function of f and a remainder or error term, as follows,

$$y = \mu_y + \gamma'(\mathbf{f} - \mathsf{E}(\mathbf{f})) + \epsilon$$

where $\gamma = (\beta' \mathbf{\Sigma}_x \beta)^- \beta' \mathbf{\Sigma}_x \alpha \in \mathbb{R}^r$, $\mu_y = \mathsf{E}(y)$, $\mathsf{E}(\epsilon | \mathbf{f}) = 0$ and $\mathsf{var}(\epsilon | \mathbf{f})$ is constant.

Discussion of Proposition

- It assumes the DGP for target is: $y_{t+h} = \alpha' \mathbf{x}_t + \varepsilon_{t+h}$
- It places assumptions on marginal distribution of **observable** predictors
 - No assumptions of underlying latent factor structure plus assumptions on unobservable quantities.
- It concludes that the *reduced* forecasting model

$$y_{t+h} = \boldsymbol{\gamma}' \mathbf{f}_t + \varepsilon_{t+h}$$

- is "equivalent" to the DGP, with \mathbf{f}_t the linear extracted features.
- ▶ We can remove (CVC) and lose homoskedasticity in regression error.

Do (LC) and (CVC) Hold in Practice?

Conditions (LC) and (CVC) are difficult to verify in practice since β is unknown. However:

- Conditions (LC) and (CVC) are satisfied for any β if x is multivariate normal.
 - Joint normality on FRED-MD is rejected.
- ► Condition (LC) is satisfied for all β if x has an elliptically contoured distribution (Eaton (1986))
 - FRED-MD satisfies ellipticity tests.
- Therefore with (LC) satisfied, we have first piece of the puzzle why different feature extraction methods have similar forecast accuracy.

• Feature extraction is carried out by solving:

$$\max_{\substack{\{\boldsymbol{\beta}_i\}\\\{\boldsymbol{\beta}_i^\prime\boldsymbol{\beta}_i=1\}\\\{\boldsymbol{\beta}_i^\prime\boldsymbol{\Sigma}_{\mathbf{x}}\boldsymbol{\beta}_j=0\}_{j=1}^{i-1}}} \mathsf{Corr}^2(\boldsymbol{h}(\boldsymbol{y}), \mathbf{x}^\prime\boldsymbol{\beta}_i) \times \boldsymbol{H}[\mathsf{Var}(\mathbf{x}^\prime\boldsymbol{\beta}_i)]$$

• OLS:
$$H(\cdot) = 1$$
, $h(\cdot) = identity$

▶ PCR:
$$H(\cdot) = identity$$
, $h(\cdot) = 1$

▶ PLS:
$$H(\cdot) = identity$$
, $h(\cdot) = identity$

► RIDGE:
$$H(\cdot) = \frac{\operatorname{Var}(\mathbf{x}'\beta_i)}{\operatorname{Var}(\mathbf{x}'\beta_i)+\kappa}$$
, $h(\cdot) = identity$

► SIR:
$$H(\cdot) = identity, h(\cdot) = E[\beta'_i \mathbf{x} | y]$$

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Prediction

- Estimate *reduced* predictors: $\hat{\mathbf{f}}_t = \hat{\boldsymbol{\beta}}' \mathbf{x}_t$
- Fit the reduced model: $y_{t+h} = \gamma'(\widehat{eta}'\mathbf{x}_t) + \varepsilon_{t+h}$
- Prediction coefficient: $\mathbf{b}=\widehat{oldsymbol{eta}}\widehat{oldsymbol{\gamma}}$
- Prediction is: $\widehat{y}_{t+h|t} = \mathbf{b}' \mathbf{x}_0 = \widehat{\gamma}' \widehat{\beta}' \mathbf{x}_0$
- Common pattern for **b** across feature extraction methods:

 $\mathbf{b} = \mathsf{scaling} \,\, \mathsf{factor} * \mathsf{signal}$

	Metaparameter	Scaling Factor	Signal
OLS	-	Σ_{x}^{-1}	σ_{xy}
RIDGE	κ	$(\mathbf{\Sigma}_{x} + \kappa I)^{-1}$	σ_{xy}
PCR	т	$\Sigma_{x}^{-}(m)$	$\sigma_{x y}$
PLS	5	$W_{ ext{PLS}}(s) \left(W_{ ext{PLS}}'(s) \mathbf{\Sigma}_{x} W_{ ext{PLS}}(s) ight)^{-1} W_{ ext{PLS}}'(s)$	σ_{xy}
SIR	d	$W_{ ext{SIR}}(d) \left(W_{ ext{SIR}}'(d) \mathbf{\Sigma}_{x} W_{ ext{SIR}}(d) ight)^{-1} W_{ ext{SIR}}'(d)$	$\sigma_{x y}$
RSIR	<i>m</i> , <i>d</i>	$W_{ ext{RSIR}}(d) \left(W_{ ext{RSIR}}'(d) \mathbf{\Sigma}_{x}(m) W_{ ext{RSIR}}(d) ight)^{-1} W_{ ext{RSIR}}'(d)$	$\sigma_{x y}$

Table: Summary of Estimators for $y = \alpha' \mathbf{x} + \epsilon$

These estimators have

• Same signal $(\sigma_{x,y})$: near-equivalent forecast accuracy

• Different scaling factor: dimension



- For targeted estimators PLS and SIR scaling factor uses y.
- How they differ:

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► PLS:
$$\mathbf{W}_{\text{PLS}}(s) = (\sigma_{xy}, \boldsymbol{\Sigma}_{x}\sigma_{xy}, \dots, \boldsymbol{\Sigma}_{x}^{s-1}\sigma_{xy})$$

► SIR:
$$\mathbf{W}_{\text{SIR}}(d) = \left(\mathsf{E}(\mathbf{x}|y), \boldsymbol{\Sigma}_{\mathbf{x}} \mathsf{E}(\mathbf{x}|y), \dots, \boldsymbol{\Sigma}_{\mathbf{x}}^{d-1} \mathsf{E}(\mathbf{x}|y)\right)$$

Therefore the reduction is based:

For **PLS** on a moment of the **joint** distribution $F(y, \mathbf{x})$.

For **SIR** on a moment of the **conditional** distribution $F(y|\mathbf{x})$.

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$$\mathsf{var}(\boldsymbol{\mathsf{X}}) = \mathsf{var}[\mathsf{E}(\boldsymbol{\mathsf{X}}|Y)] + \mathsf{E}[\mathsf{var}(\boldsymbol{\mathsf{X}}|Y)]$$

- For simplicity, assume Y is categorical: **X**|Y is the restriction of **X** in the class defined by Y
- Signal: var[E(X|Y)] is between group variation in X
- Noise: E[var(X|Y)] is within group variation
- PCR mixes up noise and signal when extracting PCs
- PLS produces ordering of eigen-components according to their importance to cov(X, Y), i.e. captures linear dependence of X and Y
- SIR produces ordering of eigen-components according to their importance to *Y*, linear and non-linear

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Beyond Linear Signals: Sufficient Dimension Reduction



Sufficient Reductions

• Suppose $\mathbf{R}(\mathbf{x}) : \mathbb{R}^p \to \mathbb{R}^d$ with $d \leq p$.

 R(x) is a Sufficient Reduction when no information about y is lost when x is replaced by R(x), i.e.

$$F(y|\mathbf{x}) = F(y|\mathbf{R}(\mathbf{x}))$$

• How to use in forecasting: For example, if the reduction is linear,

$$\mathbf{R}(\mathbf{x}) = \boldsymbol{\beta}'\mathbf{x}$$

the forecasting model is

$$y_{t+h} = g(\beta' \mathbf{x}, \varepsilon_{t+h})$$

Sufficient Reductions

• Suppose
$$\mathbf{R}(\mathbf{x}) : \mathbb{R}^p \to \mathbb{R}^d$$
 with $d \leq p$.

• **R**(**x**) is a **Sufficient Reduction** when no information about *y* is lost when **x** is replaced by **R**(**x**), i.e.

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• How to use in forecasting: For example, if the reduction is linear,

$$\mathbf{R}(\mathbf{x}) = \boldsymbol{\beta}'\mathbf{x}$$

the forecasting model is

$$y_{t+h} = g(\beta' \mathbf{x}, \varepsilon_{t+h})$$

Sufficient Reductions

• Suppose
$$\mathbf{R}(\mathbf{x}) : \mathbb{R}^p \to \mathbb{R}^d$$
 with $d \leq p$.

• **R**(**x**) is a **Sufficient Reduction** when no information about *y* is lost when **x** is replaced by **R**(**x**), i.e.

$$F(y|\mathbf{x}) = F(y|\mathbf{R}(\mathbf{x}))$$

• How to use in forecasting: For example, if the reduction is linear,

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Identifying Sufficient Linear Reductions

Linear SDR allows identification and estimation of $C(\beta)$ with $F(Y|\mathbf{X}) = F(Y|\beta^T \mathbf{X})$

• General Idea: find a kernel matrix M so that

 $\mathsf{span}(\mathsf{M})\subset \mathsf{span}(\boldsymbol{\beta})$

• SDR methods: different proposals for M



If $E(\mathbf{x}|\beta'\mathbf{x})$ is linear in $\beta'\mathbf{x}$ for any β (LC) such that $F(y|\mathbf{x}) = F(y|\beta'\mathbf{x})$, then

$$\mathcal{C}\left(\mathbf{\Sigma}_{\mathbf{x}}^{-1}[\mathsf{E}(\mathbf{x}|y) - \mathsf{E}(\mathbf{x})]\right) = \mathcal{C}\left(\mathsf{Var}[\mathsf{E}(\mathbf{x}|y)]\right)$$
$$\subseteq \mathcal{C}(\boldsymbol{\beta})$$

In SIR,

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$$\mathbf{M} = \mathbf{\Sigma}_x^{-1} \operatorname{Var}(\mathsf{E}(\mathbf{X}|Y))$$

Forecasting with Sliced Inverse Regression

• SIR Reduces the predictors:

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(i) Computes non-parametric estimate of $Var(E(\mathbf{x}|y))$

(ii) Sets $\hat{\beta}_d(SIR)$ to be the first *d* eigenvectors of $\widehat{\Sigma}_x^{-1} \operatorname{Var}(\widehat{E(\mathbf{x}|y)})$

- Run non-parametric regression $y_{t+h} = g(\hat{\beta}_d(SIR)'\mathbf{x}_t, \varepsilon_{t+h})$ and predict.
 - We did not find any forecasting improvement with non-linear $g(\cdot)$.
- RSIR formed by substituting **x** with PCs of Σ_x .

Conclusions





Comparing Forecasting Frameworks

Forecasting Framework	DGP for y_{t+h}	DGP for \mathbf{x}_t
DFM		
Standard With Irrelevant Factors No Factors for Target	$y_{t+h} = \boldsymbol{\gamma}' \mathbf{f}_t + \varepsilon_{t+h}$ $y_{t+h} = \boldsymbol{\gamma}' \mathbf{f}_{1,t} + \varepsilon_{t+h}$ $y_{t+h} = \boldsymbol{\alpha}' \mathbf{x}_t + \varepsilon_{t+h}$	$ \begin{aligned} \mathbf{x}_t &= \mathbf{\Gamma} \mathbf{f}_t + \mathbf{u}_t \\ \mathbf{x}_t &= \mathbf{\Gamma}_1 \mathbf{f}_{1,t} + \mathbf{\Gamma}_2 \mathbf{f}_{2,t} + \mathbf{u}_t \\ \mathbf{x}_t &= \mathbf{\Gamma} \mathbf{f}_t + \mathbf{u}_t \end{aligned} $
——————————————————————————————————————		
No Factors	$y_{t+h} = oldsymbol{lpha}' \mathbf{x}_t + arepsilon_{t+h}$	Conditions on $oldsymbol{\Sigma}_{\scriptscriptstyle X}$ and $oldsymbol{eta}$
<i>SDR</i>		
Non-linear Forecast Linear Forecast	$y_{t+h} = g(oldsymbol{lpha}' \mathbf{x}_t, arepsilon_{t+h}) \ y_{t+h} = oldsymbol{\gamma}'(oldsymbol{lpha}' \mathbf{x}_t) + arepsilon_{t+h}$	$ \begin{split} E\left[\mathbf{x}_t \boldsymbol{\beta}' \mathbf{x}_t\right] &= \mathbf{A} \boldsymbol{\beta}' \mathbf{x}_t \\ E\left[\mathbf{x}_t \boldsymbol{\beta}' \mathbf{x}_t\right] &= \mathbf{A} \boldsymbol{\beta}' \mathbf{x}_t \end{split} $

• Most forecasting literature studies shrinkage under factor structure.

• We study shrinkage estimators under different DGP for observables.

Comparing Forecasting Frameworks

Forecasting Framework	DGP for y_{t+h}	DGP for \mathbf{x}_t
——— DFM ———		
Standard With Irrelevant Factors No Factors for Target	$y_{t+h} = \boldsymbol{\gamma}' \mathbf{f}_t + \varepsilon_{t+h}$ $y_{t+h} = \boldsymbol{\gamma}' \mathbf{f}_{1,t} + \varepsilon_{t+h}$ $y_{t+h} = \boldsymbol{\alpha}' \mathbf{x}_t + \varepsilon_{t+h}$	$ \begin{aligned} \mathbf{x}_t &= \mathbf{\Gamma} \mathbf{f}_t + \mathbf{u}_t \\ \mathbf{x}_t &= \mathbf{\Gamma}_1 \mathbf{f}_{1,t} + \mathbf{\Gamma}_2 \mathbf{f}_{2,t} + \mathbf{u}_t \\ \mathbf{x}_t &= \mathbf{\Gamma} \mathbf{f}_t + \mathbf{u}_t \end{aligned} $
Other		
No Factors	$y_{t+h} = \boldsymbol{\alpha}' \mathbf{x}_t + \varepsilon_{t+h}$	Conditions on $oldsymbol{\Sigma}_{\scriptscriptstyle X}$ and $oldsymbol{eta}$
<i>SDR</i>		
Non-linear Forecast Linear Forecast	$y_{t+h} = g(\boldsymbol{\alpha}' \mathbf{x}_t, \varepsilon_{t+h})$ $y_{t+h} = \boldsymbol{\gamma}'(\boldsymbol{\alpha}' \mathbf{x}_t) + \varepsilon_{t+h}$	$ \begin{split} E\left[\mathbf{x}_t \boldsymbol{\beta}' \mathbf{x}_t\right] &= \mathbf{A} \boldsymbol{\beta}' \mathbf{x}_t \\ E\left[\mathbf{x}_t \boldsymbol{\beta}' \mathbf{x}_t\right] &= \mathbf{A} \boldsymbol{\beta}' \mathbf{x}_t \end{split} $

- Most forecasting literature studies shrinkage under factor structure.
- We study shrinkage estimators under different DGP for observables.

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• Since there is no non-linear trend in E(y|x) and x is elliptically contoured, Proposition 1 yields that the reduced model

$$y_{t+h} = \gamma'(\beta' \mathbf{x}_t) + \epsilon_{t+h}$$

is a good approximation model to the true population model.

• What does this mean for prediction?

$$\mathsf{E}(y - \mu_y | \beta' \mathbf{x}) = \alpha' \mathbf{\Sigma}_x \beta (\beta' \mathbf{\Sigma}_x \beta)^- \beta' (\mathbf{x} - \mathsf{E}(\mathbf{x})) = \alpha' \mathsf{P}'_{\beta(\mathbf{\Sigma}_x)}(\mathbf{x} - \mathsf{E}(\mathbf{x}))$$

where $\mathbf{P}_{\beta(\mathbf{\Sigma}_{\times})} = \beta(\beta'\mathbf{\Sigma}_{\times}\beta)^{-}\beta'\mathbf{\Sigma}_{\times}$ is the projection operator onto span(β) relative to $(\mathbf{a}, \mathbf{b}) = \mathbf{a}'\mathbf{\Sigma}_{\times}\mathbf{b}$.

 For a given x value, how close E(y|x) will be to the truth is reflected by the norm of I – P_{β(Σx)}, which is controlled solely by β.

 In consequence, ordering estimators β'x with respect to their forecasting accuracy is tantamount to identifying β's with smaller norm. Can we improve the forecasting ability of the model?

- Forecasting accuracy results do not support non-linearities in the **conditional mean** of the target variable
 - If there is non-linear signal, it must be in the variance
- Dimension two or higher in SIR indicates the presence of nonlinear relationships
 - Plots of the residuals of the fitted forecasting model versus the second SIR component indicate that the variance of the forecasting models varies for most targets

Can we improve the forecasting ability of the model?

- The data passed the multivariate elliptical symmetry test but not the normality test
 - (LC) holds but not (NCV)

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• Model-based SDR: (Bura and Forzani (2015))

• When
$$\mathbf{X}|Y \sim EC_p(\mu_Y, \mathbf{\Delta}, g_Y)$$
, then
 $\mathbf{R}(\mathbf{X}) = (\alpha'(\mathbf{X} - \mathbf{E}(\mathbf{X})), (\mathbf{X} - \mathbf{E}(\mathbf{X}))'\mathbf{\Sigma}_x^{-1}(\mathbf{X} - \mathbf{E}(\mathbf{X}))$

• The minimal sufficient reduction has a non-linear component

• Need to model the variance using $(\mathbf{X} - E(\mathbf{X}))' \mathbf{\Sigma}_{x}^{-1} (\mathbf{X} - E(\mathbf{X}))$

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