

Explicit Modular Decomposition

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Discrete Mathematics

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- Graph and Hypergraph Theory
- Discrete Optimization and Matroid Theory
- Combinatorics and Geometric Graph Theory







Planarity and 1-Face Embeddings (= particular planar drawing on orientable manifolds)



Packings, Edge- and Vertex-Colorings

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Complexity Theory

(Co)NP-completeness, Fixed-Parameter Tractability (FPT)

Algorithm Design

Exact algorithms, Heuristics, Integer Linear Programming (ILP), Approximation algorithms







Planarity and 1-Face Embeddings (= particular planar drawing on orientable manifolds)



Products of Graphs and Hypergraphs

Packings, Edge- and Vertex-Colorings



Reductions, NP-hardness, ILP, FPT, approx. algorithms

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Applied Mathematics & Math. Data Science

 General Focus: mathematical characterization of discrete data and structures that naturally occur in Life Sciences or Engineering







Planarity and 1-Face Embeddings (= particular planar drawing on orientable manifolds)



Packings, Edge- and Vertex-Colorings



Graph Grammars, Cayley Graphs, Chemical Reaction Networks



Genomics and Evolutionary Biology

Reductions, NP-hardness, ILP, FPT, approx, algorithms



undirected, simple graph G



Aim:

find efficient representation

that provides deep structural insights

and helps to understand complexity of certain problems

Representation

$$A(G) = \begin{bmatrix} \mathbf{a} & \mathbf{b} & \mathbf{c} & \mathbf{d} & \mathbf{e} \\ [0]{0} & 1 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \mathbf{e}$$
$$A_{\text{list}}(G) = \begin{bmatrix} a \\ b \\ c \\ c \\ e \end{bmatrix} \begin{bmatrix} b \\ c \\ a \\ d \\ b \\ c \end{bmatrix} \mathbf{c}$$

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Representation via (T,t)



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Ica = last common ancestor

Representation via (T,t)

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Ica = last common ancestor rooted tree T with 0/1-labeling t



Representation via (T,t)

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In this example, (T, t) contains all structural information of G and can be used to recover G, i.e.,

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G is explained by (T,t): $t(lca_T(x,y)) = 1 \iff \{x,y\} \in E$

The subclass of graphs that can be explained by (T,t) are precisely the cographs



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The subclass of graphs that can be explained by (T, t) are precisely the **cographs**





Cotree (T,t) explains cograph G

discovered independently by several authors since the 1970s; Jung (1978), Lerchs (1971), Seinsche (1974), and Sumner (1974).



Cographs ...

• ... form an extremely well-known graph class



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- … have appealing properties (GI - easy, many NP-hard problems become polynomial-time solvable)
- ... data-storage O(|V(G)|)



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Representation via (T,t)



Ica = last common ancestor rooted tree T with 0/1-labeling t undirected, simple graph G



Representation via (T,t)

undirected, simple graph G



rooted tree T with 0/1-labeling t

BAD news: Not all graphs can be explained by such 0/1-labeled trees (T, t)


Basics: Graphs and their Representation

Representation via (T,t)

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BAD news: Not all graphs can be explained by such 0/1-labeled trees (T, t)

The subclass of graphs that can be explained by (T, t) are *precisely* the **cographs** (= extremely well-studied graph class).

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BAD news: Not all graphs can be explained by such 0/1-labeled trees (T, t)

The subclass of graphs that can be explained by (T,t) are precisely the cographs (= extremely well-studied graph class).

GOOD news: Every graph G has a unique **Modular Decomposition Tree** that at least to some extent provides structural information of G

 $M \subseteq V(G)$ is a **module** in *G* if $N(x) \setminus M = N(y) \setminus M$ for all $x, y \in M$



^{*}MD is a standard technique to understand discrete structure by decomposing them into smaller "building blocks". MD is of such basic importance that it was rediscovered several times under several names, e.g., Gallai (1967), Habib&Maurer (1979), Möhring&Rademacher (1979), Sumner (1971)

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Every graph has a **unique decomposition into non-overlapping modules** that can be computed in *linear-time*.

MD = set of *all* non-overlapping modules

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There are different type of modules:

0, 1 and P (Prime) modules

defined in terms of connectedness conditions (omitted).

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0- and 1-vertices in MD-tree are good:

 $t(\mathsf{lca}(x,y)) = 0 \implies \{x,y\} \notin E(G) \text{ and } t(\mathsf{lca}(x,y)) = 1 \implies \{x,y\} \in E(G)$

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BUT, not all structural information of G is provided by the MD-tree if it contains P-vertices.

$$t(lca(3,4)) = P \text{ and } \{3,4\} \in E(G)$$

 $t(lca(3,5)) = P \text{ and } \{3,5\} \notin E(G)$

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 $t(lca(3,5)) = P \text{ and } \{3,5\} \notin E(G)$

Full information of G is provided only if MD-tree does not contain P-vertices (cographs)

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The MD-tree cannot be used to recover G (structural information gets lost on P-vertices)

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The MD-tree cannot be used to recover *G* (structural information gets lost on *P*-vertices) *P*-vertices $\hat{=}$ extremely secured closed box hiding structural information.

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Can we break and unbox the *P*-vertices to obtain 0/1-labeled rooted networks that provides the missing structural information of *G* ?

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⇒ Explicit Modular Decomposition



General Aim:



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 Preserve the main features of the MD-tree, try to modify only the *P*-vertices to obtain 0/1-labeled rooted networks to explain graphs

Proof of Concept: Half-grid networks.



Bruckmann, Stadler, Hellmuth, From Modular Decomposition Trees to Rooted Median Graphs, Discr. Appl. Math, 2021





Bruckmann, Stadler, Hellmuth, From Modular Decomposition Trees to Rooted Median Graphs, Discr. Appl. Math, 2021



Theorem (2021)

Every graph G can be explained by a 0/1-labeled half-grid and thus, by a network obtained from MDT by locally replacing "P"-vertices by half-grids = median graphs.

Proof: In half-grids we have $lca(x,y) \neq lca(x',y')$ for distinct pairs x, y and x', y'.

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 \implies The idea of explicit modular decomposition is feasible!

But half-grids are only as suitable as representing G with its adjacency matrix (no deep structural insights)

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General Aim:



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Instead of using "dense" half-grids let's look at the other extreme: Use the most-simplest non-tree structure to replace *P*-vertices.



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From here one, we focus on the special case:

replacing P-vertices by rooted 0/1-labeled cycles



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Question: Which type of graphs can be explained by such networks (N, t)?

Simple case: Single *P*-vertex

Consider graphs G whose MD-tree is a star-tree with single P-vertex



Simple case: Single *P*-vertex

Consider graphs *G* whose MD-tree is a star-tree with single *P*-vertex



1st Task: Characterize graphs G where

- MD-tree is star with single P-vertex and
- the resulting network (N, t) explains G?
Simple case: Single *P*-vertex

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Scholz & Hellmuth, From Modular Decomposition Trees to Level-1 networks: Pseudo-Cographs, Polar-Cats and Prime Polar-Cats, Discr. Appl. Math, 2022

A graph *G* is a pseudo-cograph if $|V(G)| \leq 2$

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- (P1) $V(G_1) \cup V(G_2) = V(G),$ $V(G_1) \cap V(G_2) = \{v\};$
- (P2) G_1 and G_2 are cographs;
- (P3) G v is either the join or the disjoint union of $G_1 v$ and $G_2 v$.

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A graph *G* is a pseudo-cograph if $|V(G)| \le 2$ or if there is a vertex $v \in V(G)$ and induced subgraphs $G_1, G_2 \subseteq G$, both with at least two vertices such that

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- (P3) G v is either the join or the disjoint union of $G_1 v$ and $G_2 v$.

1st Task: Characterize graphs G where

- MD-tree is star with single P-vertex and
- the resulting network (N, t) explains G?

Solution: Pseudo-cographs



Scholz & Hellmuth, From Modular Decomposition Trees to Level-1 networks: Pseudo-Cographs, Polar-Cats and Prime Polar-Cats, Discr. Appl. Math, 2022

A graph *G* is a pseudo-cograph if $|V(G)| \le 2$ or if there is a vertex $v \in V(G)$ and induced subgraphs $G_1, G_2 \subseteq G$, both with at least two vertices such that

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Graphs for which this approach works are called

GATEX := Galled-Tree Explainable (graphs that can be explained by such networks)

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Galled-tree := 0/1-labeled rooted network where all cycles are edge-disjoint

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Theorem (2022, 2023)

A graph is $GATEx \iff$ for all P-modules M the "quotient of G[M]" is a pseudo-cograph.

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GATEX graphs can be recognized and construction of (N, t) can be done in linear time.

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GATEX graphs can have $O(|n|^2)$ edges, but can be stored using only **linear space**.

Scholz & Hellmuth, From Modular Decomposition Trees to Level-1 networks: Pseudo-Cographs, Polar-Cats and Prime Polar-Cats, Discr. Appl. Math, 2022

Consequences

GATEx graphs form a novel and interesting class of graphs that is closely related to many other well-known and famous graph classes.

Among other results, GATEx graphs are:

perfect graphs

Chromatic number of every induced subgraph = size of the largest clique of that subgraph

comparability (=transitive orientable) graphs

There exists a transitive orientation on this graphs = represents partial orders in where two elements are connected by an edge if they are comparable to each other in the partial order.

permutation graphs

used to represent permutations

perfectly orderable

there is an ordering of the vertices of G such that a greedy coloring algorithm with that ordering optimally colors every induced subgraph of the given graph

Every cograph and every graph whose vertices are contained in at one most induced P₄ are GATEX



Scholz & Hellmuth, Resolving Prime Modules: The Structure of Pseudo-cographs and Galled-Tree Explainable Graphs, Discr. Appl. Math, 2024

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Example: Find optimal vertex coloring.



Optimal vertex coloring can be solved in linear-time on GATEX graphs.

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Theorem (2023)

The following NP-hard problems can be solved in linear-time on GATEX graphs.

- Finding a minimum vertex coloring
- Finding a perfect order
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Scholz & Hellmuth, Linear Time Algorithms for NP-hard Problems restricted to GaTEx Graphs, 29th International Computing and Combinatorics Conference (COCOON 23), 2024

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Moreover, GATEX graphs have bounded twin-width, i.e., many complexity results established for those graphs (e.g. FPT or approximation results) become applicable for GATEX graphs.

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We conjecture that also the graph-isomorphism problem has a linear-time solution for GATEX graphs (work in progress).

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Basic idea: Use the network (N, t) as a guide for the optimization algorithms

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Explicit modular decomposition provides an essential tool-box for solving discrete optimization problems!

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try to modify only the P-vertices

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• Here: replace "*P*" vertices in MD tree by simple cycles or half-grids This is only a snapshot of what is possible!



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- Here: replace "*P*" vertices in MD tree by simple cycles or half-grids This is only a snapshot of what is possible!
- we are not restricted to resolving *P*-vertices in the MD-tree by simple cycles or half-grids only For generalizations, we can draw on nearly unlimited resources from phylogenetic networks.

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- we characterized GATEX graphs (=graphs that can be explained by 0/1 galled trees) GATEX graphs are closely related to other famous graph classes several NP-hard problems become easy on GATEX graphs
- Explicit Modular Decomposition is a very novel concept and a great playground (generalizations e.g. edge-colored di-graphs or matroids are coming)!



Hellmuth & Wieseke et al., Phylogenomics with Paralogs, Proceedings of the National Academy of Sciences (PNAS), 2015





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Given a relationship R that can be represented by trees T

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Collaborations



Anna Lindeberg



Guillaume Scholz



Carmen Bruckmann



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THANK YOU!

Appendix

Cographs ...



Cotree (T, t) explains cograph G

discovered independently by several authors since the 1970s; Jung (1978), Lerchs (1971), Seinsche (1974), and Sumner (1974).

Cographs ...

• ... are explained by a 0/1-labeled tree (T,t):



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Cographs ...

• ... are explained by a 0/1-labeled tree (T,t):

 $\{x,y\} \in E \iff t(\mathsf{lca}(x,y)) = 1$

• ... form an extremely well-known graph class



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Pseudo-cographs: Algorithms

Recognition - The Basic Idea

If G cograph - done

Scholz & Hellmuth, From Modular Decomposition Trees to Level-1 networks: Pseudo-Cographs, Polar-Cats and Prime Polar-Cats, Discr. Appl. Math, 2022

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If G cograph - done Else find one P_4 For all $v \in P_4$ If G - v or $\overline{G - v}$ disconnected take one connected component C Put $V(G_1) = C \cup \{v\}$ Put $V(G_2) = (V \setminus C) \cup \{v\}$ If G_1 and G_2 are cographs return (v, G_1, G_2)



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Pseudo-cographs can be recognized in linear time and a corresponding 0/1-labeled network can be constructed within the same time complexity.

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This looks like a very interesting, novel graph class !!





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- "unbox" the structure of prime modules



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As a first attempt we may ask:

Is there a 0/1-labeled network that can explain EVERY given graph?



Theorem (2021)

Every graph G can be explained by a 0/1-labeled half-grid and thus, by a network obtained from the MD-tree by locally replacing "P"-vertices by half-grids = median graphs.

Bruckmann, Stadler, Hellmuth, From Modular Decomposition Trees to Rooted Median Graphs, Discr. Appl. Math, 2021



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Half-grids are rather "heavy" $(O(|V(G)|^2)$ edges and vertices) and of less interest from the structural point and biological point of view.

 \implies Can we go simpler?

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MD = set of all *non-overlapping* modules

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There are different type of modules:

Parallel (0), Series (1) and Prime (P) modules defined in terms of connectedness conditions (omitted).

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BUT, full information of G is provided only if G does not contain prime modules.

- $t(lca(3,4)) = P \text{ and } \{3,4\} \in E(G)$
- $t(lca(3,5)) = P \text{ and } \{3,5\} \notin E(G)$

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For cographs:

- The MD does not contain prime modules
- $\{x,y\} \in E \iff t(\mathsf{lca}(x,y)) = 1$

Thus, full information about cographs is provided by MD

 $M \subseteq V(G)$ is a **module** in *G* if $N(x) \setminus M = N(y) \setminus M$ for all $x, y \in M$



BUT, full information of G is provided only if G does not contain prime modules.

- *t*(lca(3,4)) = **P** and {3,4} ∈ *E*(*G*)
- $t(lca(3,5)) = \mathbf{P} \text{ and } \{3,5\} \notin E(G)$

For cographs:

- The MD does not contain prime modules
- $\{x,y\} \in E \iff t(\mathsf{lca}(x,y)) = 1$

Thus, full information about cographs is provided by MD

 $M \subseteq V(G)$ is a **module** in *G* if $N(x) \setminus M = N(y) \setminus M$ for all $x, y \in M$





BUT, full information of *G* is provided only if *G* does not contain prime modules.

We used MD and cographs for studies in the context of evolutionary biology **Milestone:** How to use "noise" in the data as an additional source of information!

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We used MD and cographs for studies in the context of evolutionary biology **Milestone:** How to use "noise" in the data as an additional source of information! We observed:

- It is crucial to understand the structure of subgraphs induced by prime modules!
- Evolution is not always tree-like and often better explained by networks!

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Central Questions:

Can we explain graphs by structures that go beyond trees?

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Aim: Understand graph classes that can be explained by 0/1-labeled networks.

Pseudo-cographs: Characterization



Theorem (2022)

G is a pseudo-cograph $\iff |V(G)| \le 2$ or G can be explained by a galled-tree (N, t) that contains precisely one cycle C such that $\rho_C = \rho_N$ and the (unique) hybrid has precisely one child.

Scholz & Hellmuth, From Modular Decomposition Trees to Level-1 networks: Pseudo-Cographs, Polar-Cats and Prime Polar-Cats, Discr. Appl. Math, 2022

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Pseudo-cographs can be recognized in linear time and a corresponding 0/1-labeled network can be constructed within the same time complexity.

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General Aim:

- Preserve the main features of the MD-tree, try to modify only the prime-vertices "P" to obtain 0/1-labeled rooted networks to explain graphs
- "unbox" the structure of prime modules






Galled-tree: = 0/1-labeled network "consisting" of edges and simple cycles



G explained by (N,t) if $\{x,y\} \in E(G) \iff t(lca_N(x,y)) = 1.$

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 t(lca_T(x, y)) = i ⇐⇒ {x, y} ∈ E has color i



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In the MD-tree (*T*, *t*) clusters = modules
 In (*N*, *t*), the modules of *G* form a subset of the clusters in (*N*, *t*)
 ⇒ generalization of modules!





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Hypergraphs and Set-Systems

