Analyzing human perceptions from survey data with **Nonlinear CUB models**



Wien, 13th May 2016 Marica Manisera and Paola Zuccolotto -University of Brescia, Italy

Credits

Credits

- Manisera M., Zuccolotto P. (2014) Modelling rating data with Nonlinear CUB models, *Computational Statistics and Data Analysis*, 78, 100–118.
- Manisera M., Zuccolotto P. (2014) Modelling "don't know" responses in rating scales. Pattern Recognition Letters, 45, 226-234
- Manisera M., Zuccolotto P. (2014). Nonlinear CUB models: the R code. *Statistica & Applicazioni*, XII, 205-223.
- Manisera M., Zuccolotto P. (2015). Identifiability of a model for discrete frequency distributions with a multidimensional parameter space, *Journal of Multivariate Analysis*, 140, 302-316.
- Manisera M., Zuccolotto P. (2015). Visualizing Multiple Results from Nonlinear CUB Models with R Grid Viewports. *Electronic Journal of Applied Statistical Analysis*, 8, 360-373.
- Manisera M., Zuccolotto P. (2016). Treatment of 'don't know' responses in a mixture model for rating data, *Metron*, 74, 99-115.
- Manisera M., Zuccolotto P. (2016). Estimation of Nonlinear CUB models via numerical optimization and EM algorithm, *Communications in Statistics - Simulation and Computation, forthcoming.*



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redit





- Examples of rating data (real data case studies)
- The unconscious Decision Process (DP) driving individuals' responses on a rating scale
- **CUB models** (D'Elia&Piccolo 2005, *Computational Statistics* and Data Analysis – Iannario&Piccolo 2011, Modern Analysis of Customer Surveys)
- **NLCUB models** (Manisera&Zuccolotto 2014, *Computational Statistics and Data Analysis*)

SHAPE: "Statistical Modelling of Human Perception", STAR project -University of Naples Federico II - CUP: E68C13000020003 SYRTO: "SYstemic Risk TOmography: Signals, Measurements, Transmission Channels, and Policy Interventions", grant from the European Union Seventh Framework Programme - Project ID: 320270







The analysis of human perception is often carried out by resorting to **surveys** and **questionnaires**, where respondents are asked to **express ratings about the objects being evaluated**.

The goal of the statistical tools proposed for this kind of data is to explicitly **characterize the respondents' perceptions about a latent trait**, by taking into account, at the same time, the **ordinal categorical scale of measurement** of the involved statistical variables.

lata - examples

Rating data – example 1

- A survey investigating confidence about assertions concerned with superstition in Romania
- dataset by Vlăsceanu et al. (2012), downloadable from the IQSS (Institute of Quantitative Social Science) Dataverse Network of the Harvard University
- Respondents (n = 1161) were asked to express a judgment about their degree of belief in some assertions, using a 4-point Likert scale (totally disagree, disagree, agree, totally agree)

Rating data – example 1 (superstition)



- 1. Evil has red eyes
- 2. Number 13 brings bad luck
- 3. If the palm of your left hand itches, you will receive money soon
- 4. Lucky at cards, unlucky in love
- 5. If a black cat crosses the street it is a sign of bad luck
- 6. Zodiacal signs influence nature and personality
- 7. Human civilization was created by aliens
- 8. There are some numbers that bring good luck to certain people

Rating data – example 2 (fraud management)

• A survey investigating the perceveid risk of being victim of frauds when using ICT

data - examples

- dataset supplied by NetConsulting (2013)
- Respondents (n = 116 managers of small, mid-sized and large firms) were asked to express a judgment about their degree of perceived fraud risk when using some different IC Technologies, using a 4-point Likert scale (very low, low, high, very high)



SOCNET: CLOUD: BYOD: LEG: Web 2.0 and Social Networks Cloud storage and computing Bring Your Own Device Legacy technologies

BALLI data - example.

Rating data – example 3 (Standard Eurobarometer 81)



data - examples

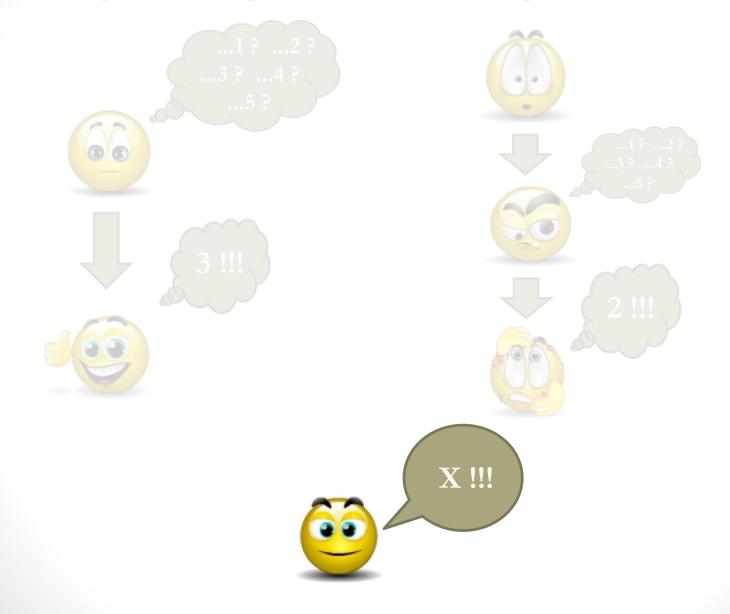
- A sample survey covering the national population of citizens of the 27 European Union Member States
- Questions asking respondents to rate their level of agreement with some statements using a 4-point Likert scale (totally disagree, tend to disagree, tend to agree, totally agree)
- "don't know" option available

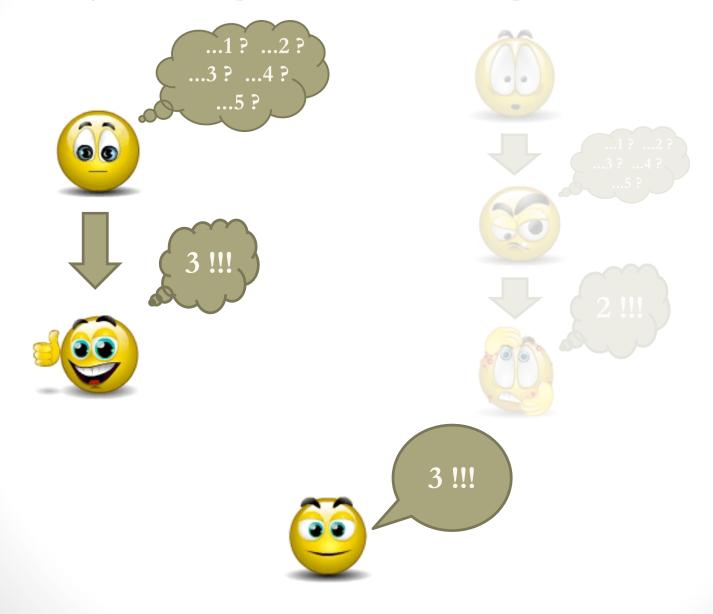
Rating data – example 3 (Standard Eurobarometer 81)

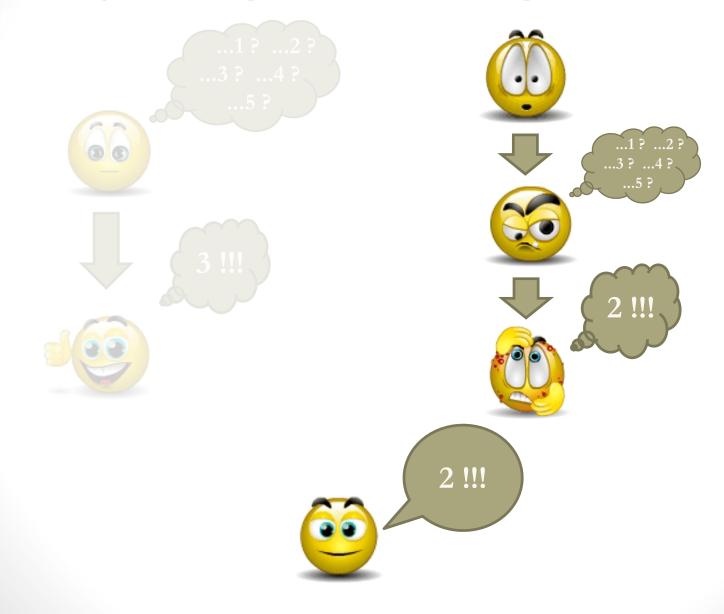
European

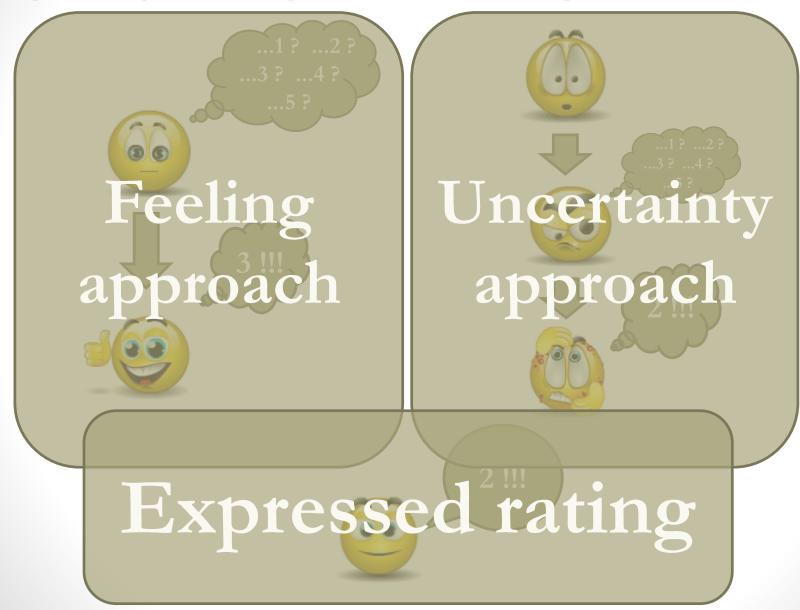
Commission

QA19.1: I understand how the EU works
QA19.2: Globalisation is an opportunity for economic growth
QA19.3: (OUR COUNTRY) could better face the future outside the EU
QA19.4: The EU should develop further into a federation of nation states
QA19.5: More decisions should be taken at EU level
QA19.6: We need a united Europe in today's world









Express a rating from 1 (=completely unsatisfied) to 5 (=completely satisfied)

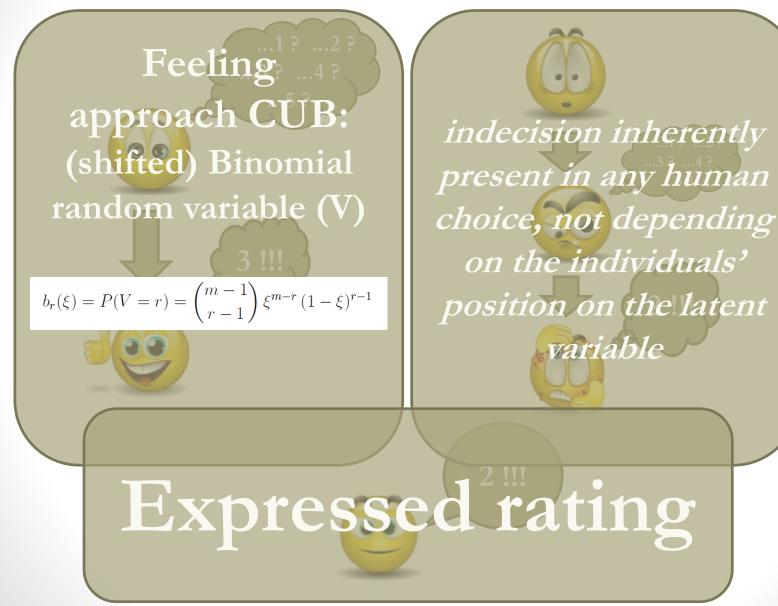
reasoned and logical thinking, the set of emotions, perceptions, subjective evaluations that individuals have with regard to the latent trait being evaluated

indecision inherently present in any human choice, not depending on the individuals' position on the latent variable

Expressed rating

CUB models

Are you satisfied with XYZ? How do CUB models fit into this framework?



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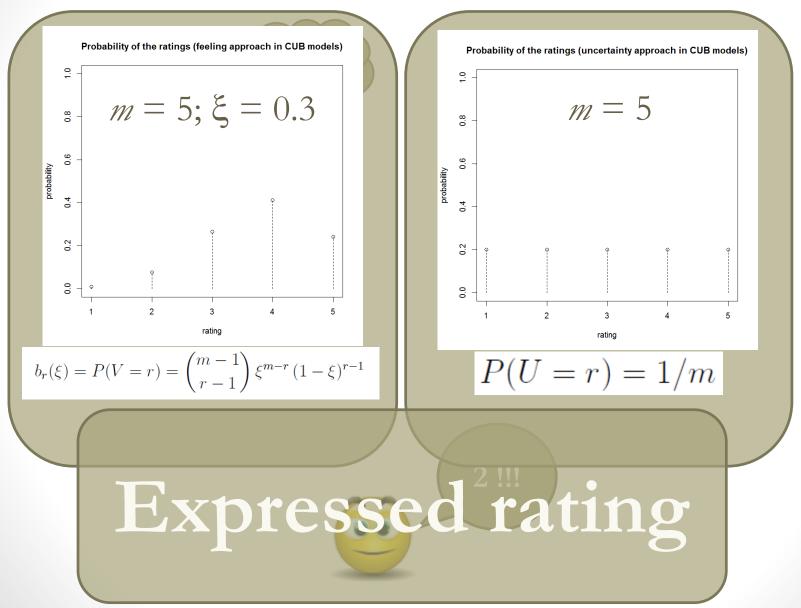
B models



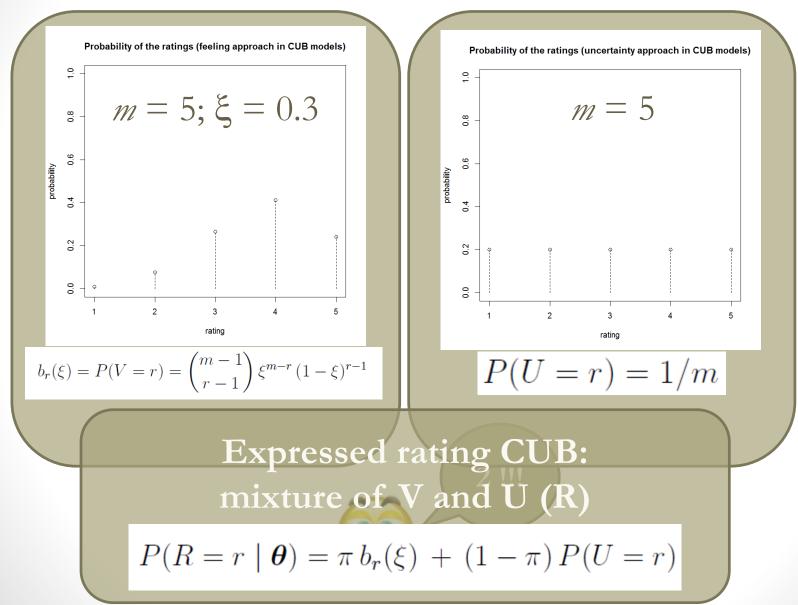
Are you satisfied with XYZ? How do CUB models fit into this framework? Express a rating from 1 (=completely unsatisfied) to 5 (=completely satisfied) B models Probability of the ratings (feeling approach in CUB models) Uncertainty 1.0 $m = 5; \xi = 0.3$ approach CUB: 0.8 Uniform random 0.6 probability variable (U) 0.4 0.2 0.0 P(U=r) = 1/mrating $b_r(\xi) = P(V = r) = \binom{m-1}{r-1} \xi^{m-r} (1-\xi)^{r-1}$

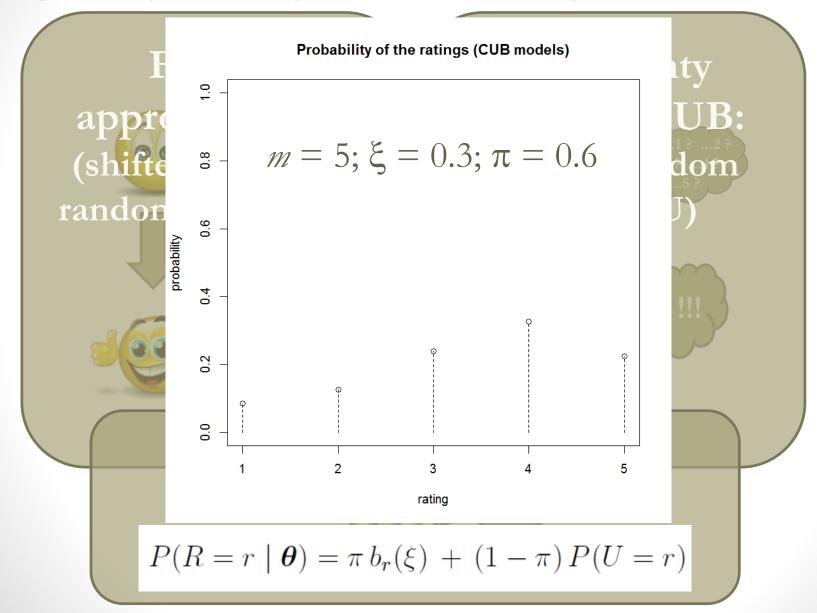
Expressed rating

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CUB models



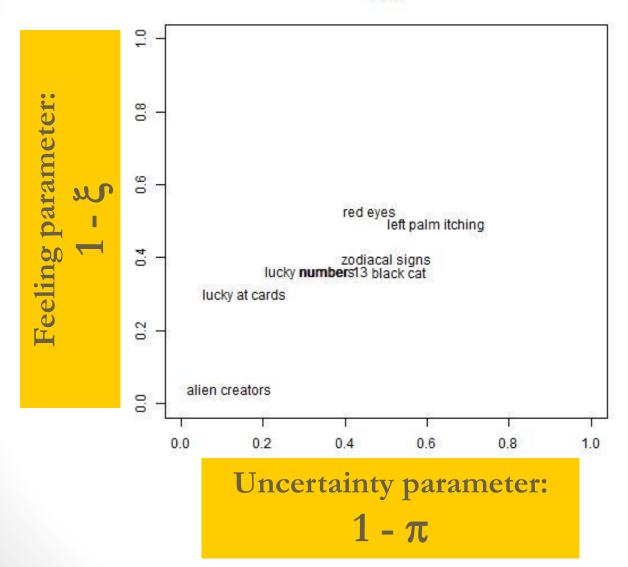


Are you satisfied with XYZ? How do CUB models fit into this framework? JB models Express a rating from 1 (=completely unsatisfied) to 5 (=completely satisfied) Uncertainty Feeling approach CUB: approach CUB: (shifted) Binomial Uniform random random variable (V) variable (U) Feeling parameter: **Uncertainty parameter:** 1 - ξ 1 - π **Expressed rating CUB:** mixture of V and U (R) $P(R = r \mid \theta) = \pi b_r(\xi) + (1 - \pi) P(U = r)$

Example 1 (superstition)

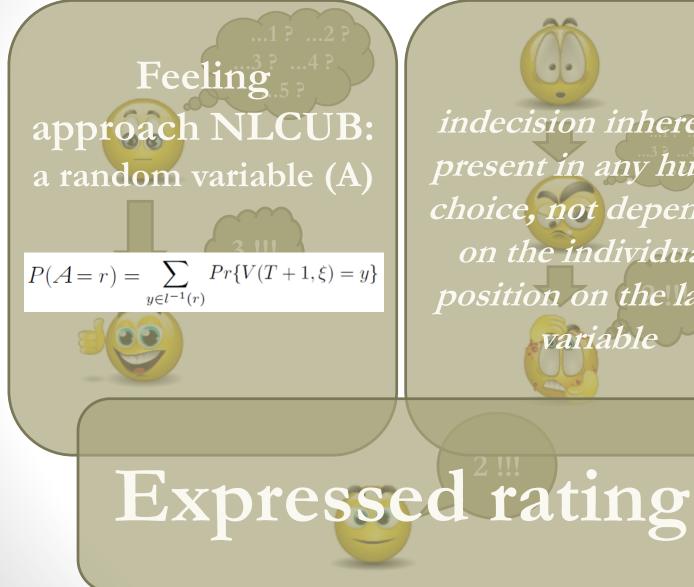


CUB

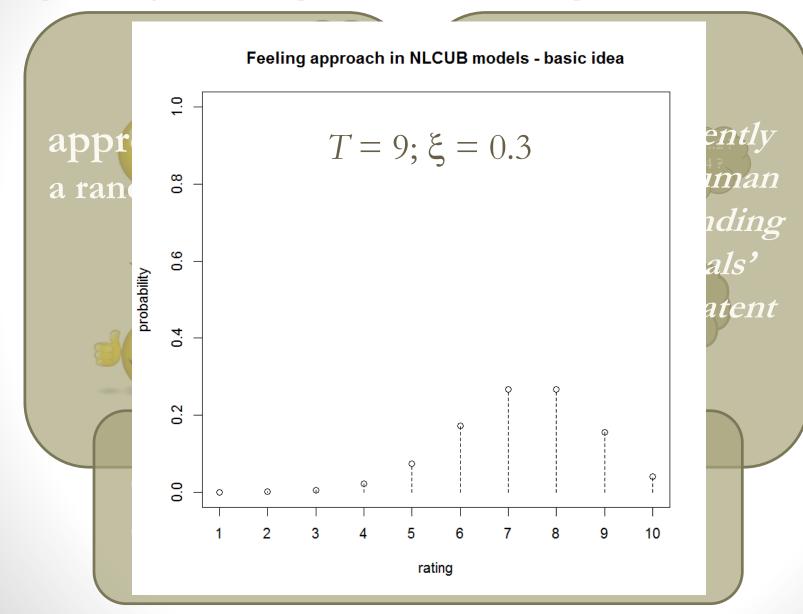


How do NLCUB models fit into this framework?

Express a rating from 1 (=completely unsatisfied) to 5 (=completely satisfied)

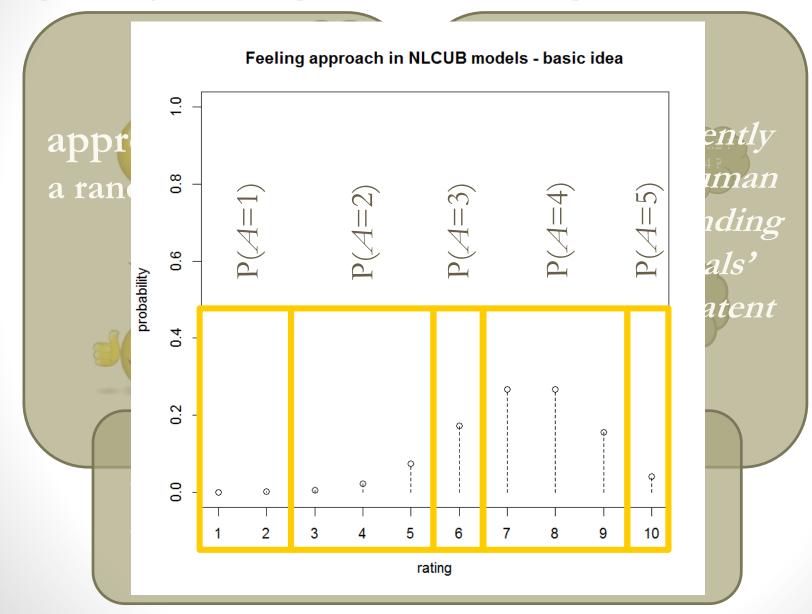


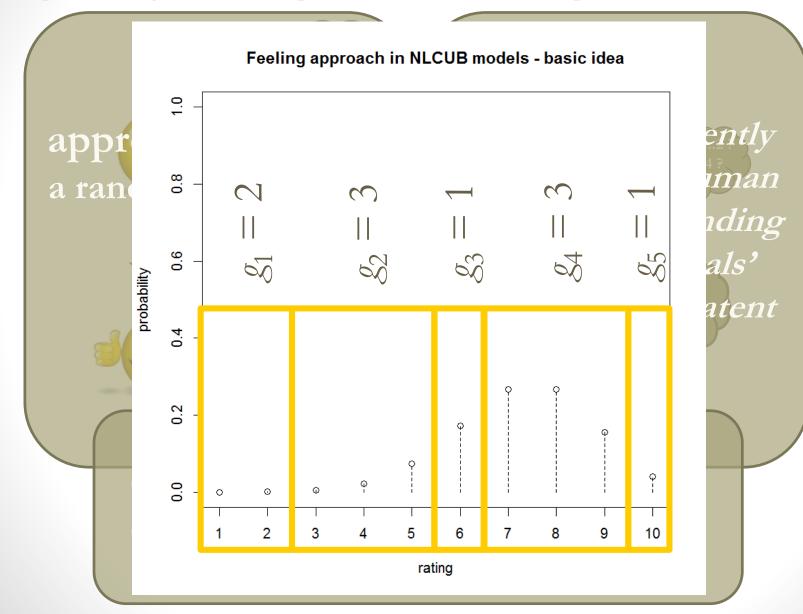
indecision inherently present in any human choice, not depending on the individuals' position on the latent variable



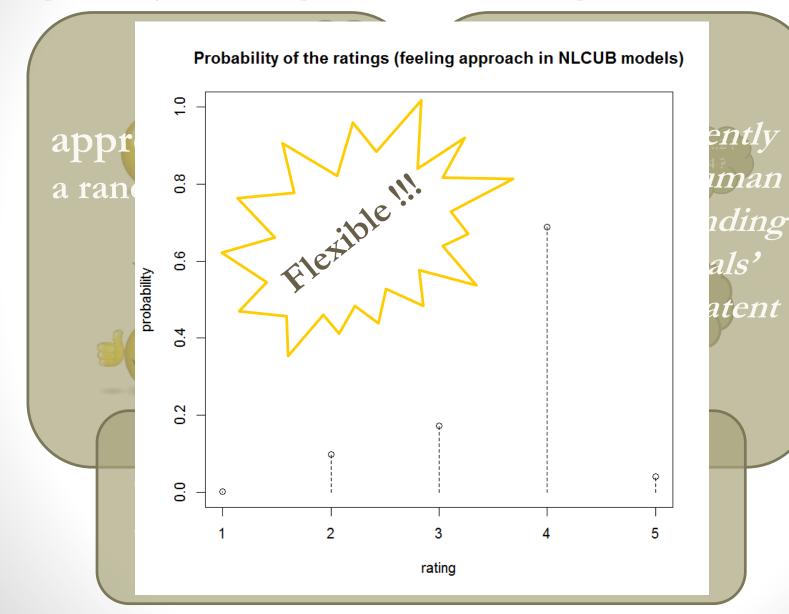
How do NLCUB models fit into this framework?

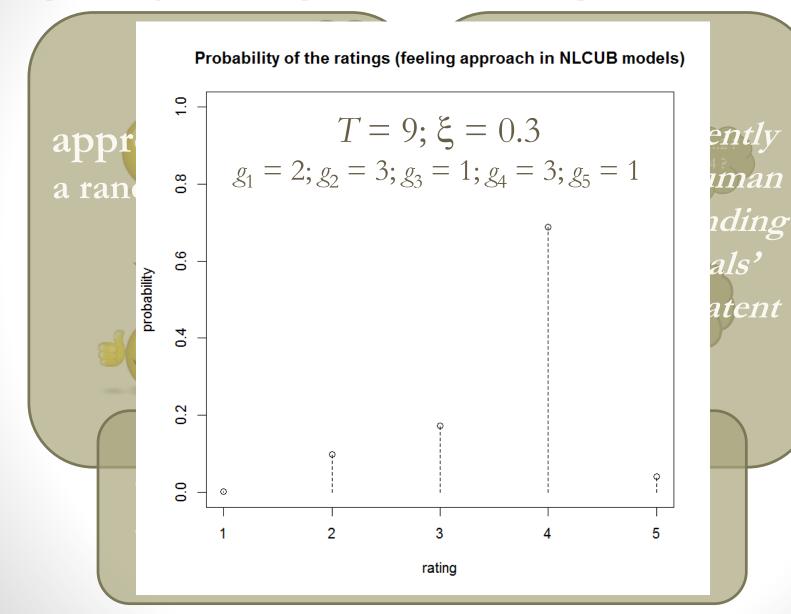
UB models





UB models

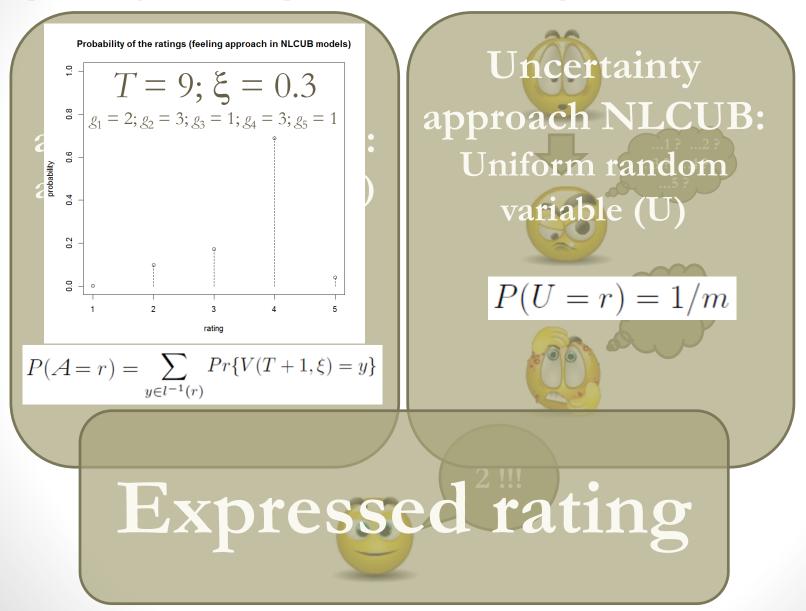




How do NLCUB models fit into this framework?

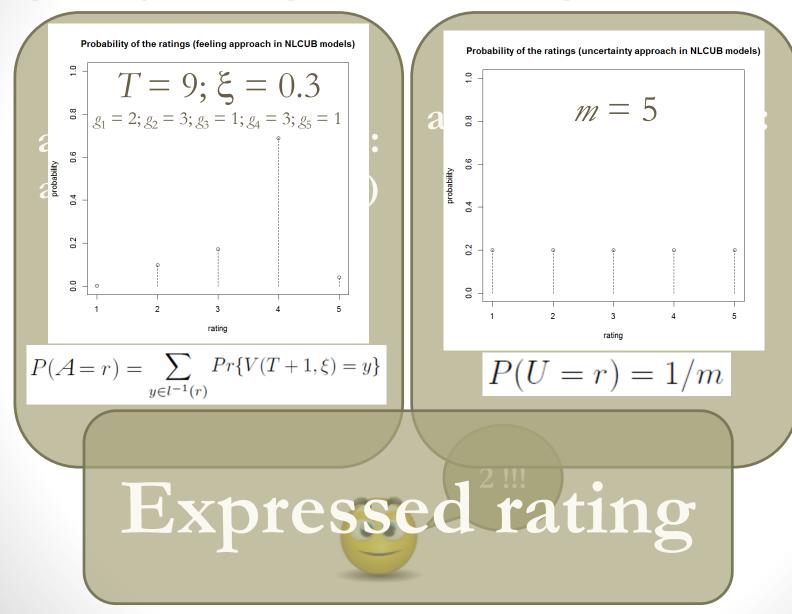
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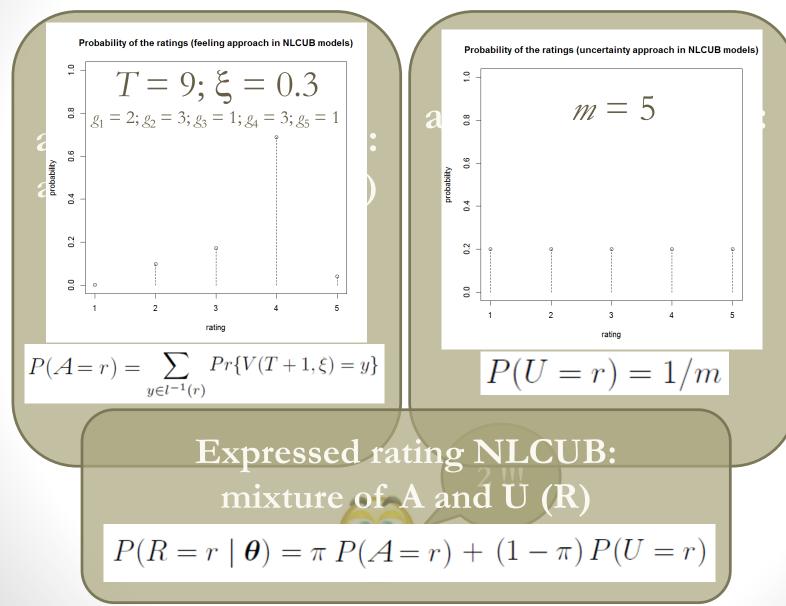
models

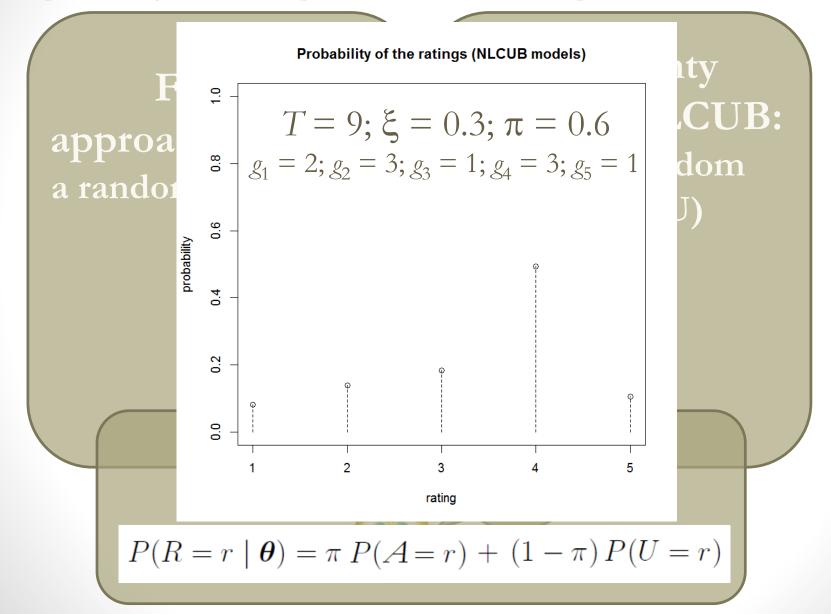


How do NLCUB models fit into this framework?

models



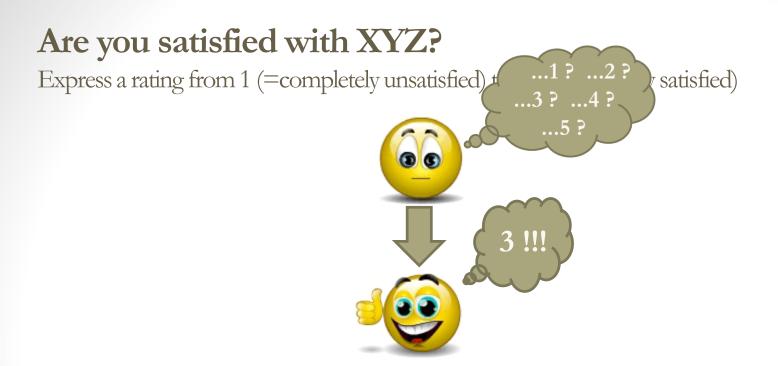




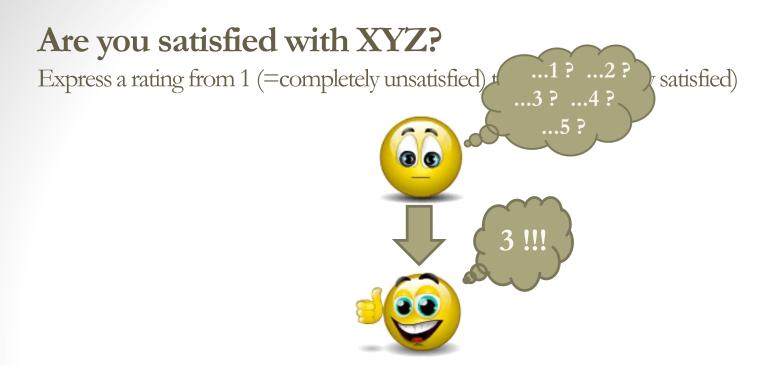
Express a rating from 1 (=completely unsatisfied) to 5 (=completely satisfied)

Let us focus on the Feeling approach





- We assume that the Feeling approach proceeds through T consecutive steps.
- At each step a basic judgment is formulated.
- Step-by-step, the basic judgments are accumulated and transformed into provisional ratings.
- The rating at the end of the Feeling approach is given by the last provisional rating.

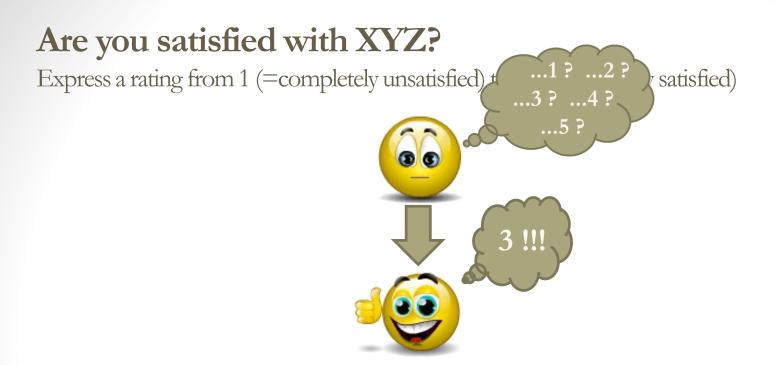


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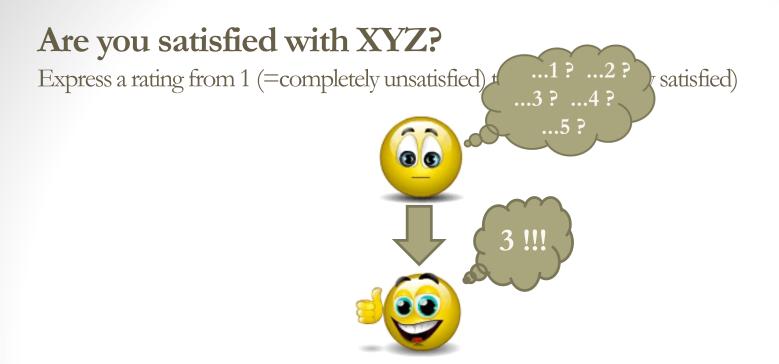


An evaluation about the latent trait, but a simpler task than the rating expression

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Are you satisfied with XYZ?

Express a rating from 1 (=completely unsatisfied) to 5 (=completely satisfied)

We can obtain **several different models**, depending on the assumptions we make about:

- the distribution of the basic judgments
- the accumulation function
- the transformation function
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Both CUB and NLCUB models can be derived following this paradigm, when some specific assumptions (....) are made about these three points

A) FEELING APPROACH

- 1. Elementary judgments: An *iid* sequence of random variables X_1, \dots, X_T with domains $\mathcal{D}_{X_1}, \dots, \mathcal{D}_{X_T}$ generates T elementary judgments x_1, \dots, x_T progressively expressed along T steps.
- 2. Accumulating function: At each step t, a function $f : \mathcal{D}_{X_1} \times \cdots \times \mathcal{D}_{X_t} \to \Psi_t \subseteq \mathbb{R}$ summarizes the t past elementary judgments (for example, by summation). We say that f is an accumulating function, i.e. we require it obeys the following property: $\Psi_t \subseteq \Psi_{t+1}, \forall t$.
- 3. Accumulated judgments: A sequence of random variables $W_1, \dots, W_T, W_t = f(X_1, \dots, X_t)$, with domains $\mathcal{D}_{W_1} \equiv \Psi_1, \dots, \mathcal{D}_{W_T} \equiv \Psi_T$ is then originated along the T steps of the DP with T corresponding realizations $w_1, \dots, w_T, w_t = f(x_1, \dots, x_t)$, called accumulated judgments.
- 4. 'Likertization' function: At each step t, a non-decreasing function $d : \mathcal{D}_{W_T} \to (1, \dots, m)$ transforms w_t into a provisional rating. Note that from the definition of accumulating function derives $\mathcal{D}_{W_1} \subseteq \dots \subseteq \mathcal{D}_{W_T}$, so that d can always be computed on the domain of W_t , for all t.
- 5. Provisional ratings: A sequence of random variables R_1, \dots, R_T , $R_t = d(W_t)$, with domains the space $(1, \dots, m)$ is then originated along the T steps of the feeling path with T corresponding realizations r_1, \dots, r_T , $r_t = d(w_t)$, called provisional ratings.

TRANSITION PROBABILITIES

The probability of increasing one (provisional) rating point in the next step of the decision process

$$\phi_t(s) = Pr(R_{t+1} = s + 1 | R_t = s)$$

$$\phi_t(s) = \frac{\sum_{w_t \in d^{-1}(s)} \Pr(\underline{x}(s) < X_{t+1} \le \overline{x}(s) | W_t = w_t) \Pr(W_t = w_t)}{\sum_{w_t \in d^{-1}(s)} \Pr(W_t = w_t)}$$

with $t: \mathcal{D}_{W_t} \cap d^{-1}(s) \neq \emptyset$, t < T, where $\underline{x}(s) = \max\{d^{-1}(s)\} - w_t$ and $\overline{x}(s) = \max\{d^{-1}(s+1)\} - w_t$. In order to consider also what happens during the first step of the DP, we define $w_0 := 0$ and $\phi_0 = \phi_0(s) := Pr(\underline{x}(s) < X_1 \leq \overline{x}(s))$ with $s = d(w_0) = d(0)$.

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$$\phi_t(s) = Pr(R_{t+1} = s+1 | R_t = s)$$

In CUB models:

$$\phi_t(s) = 1 - \xi$$

for all *t* and *s*

TRANSITION PROBABILITIES

The probability of increasing one (provisional) rating point in the next step of the decision process

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In NLCUB models:
$$\phi_t(s) = (1-\xi) \frac{\binom{t}{w_{gss}} (1-\xi)^{w_{gss}} \xi^{t-w_{gss}}}{\sum_{h=1}^{g_s} \binom{t}{w_{hs}} (1-\xi)^{w_{hs}} \xi^{t-w_{hs}}}$$

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The probability of increasing one (provisional) rating point in the next step of the decision process

$$\phi_t(s) = Pr(R_{t+1} = s+1 | R_t = s)$$

In NLCUB models:

Different values for different *t* and *s*

TRANSITION PROBABILITIES

$$\phi_t(s) = Pr(R_{t+1} = s + 1 | R_t = s)$$

$$\phi(s) = av_t(\phi_t(s))$$

"Perceived closeness" between rating s and s + 1

$$\delta_s = h(\phi(s))$$
 for example $\delta_s = -\log(\phi(s))$

". "Perceived distance" between rating s and s + 1

TRANSITION PLOT

A broken line joining points $(s, \tilde{\phi}(s))$, where

 $s=0,\cdots,m-1$

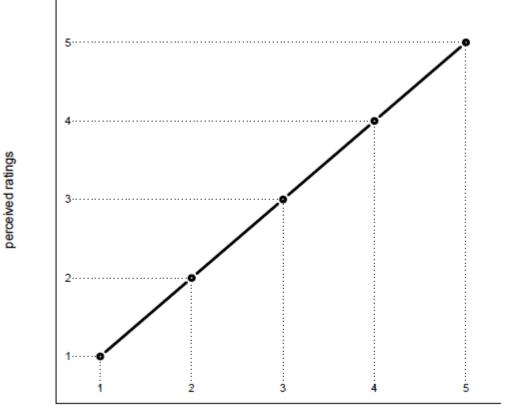
 $\tilde{\phi}(s) = (\delta_1 + \dots + \delta_s) / (\delta_1 + \dots + \delta_{m-1})$

i.e.: the cumulated "perceived distances".

It gives an idea of the state of mind of respondents toward the rating scale.

TRANSITION PLOT - CUB model

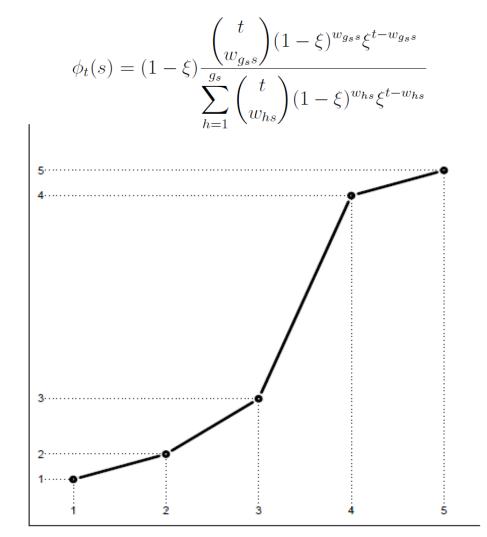
 $\phi_t(s) = 1 - \xi$



The transition ploi

TRANSITION PLOT - NLCUB model

The transition plot



perceived ratings

ratings

NonLinear CUB models

 Derive from a different assumed mechanism in the Feeling approach (the Uncertainty approach is unchanged) CUB models

- Allow us to gain insight about the state of mind toward the rating scale
- Include traditional CUB models as a special case

NonLinear CUB models

• Derive from a different assumed mechanism in the Feeling approach (the Uncertainty approach is unchanged)

CUB models

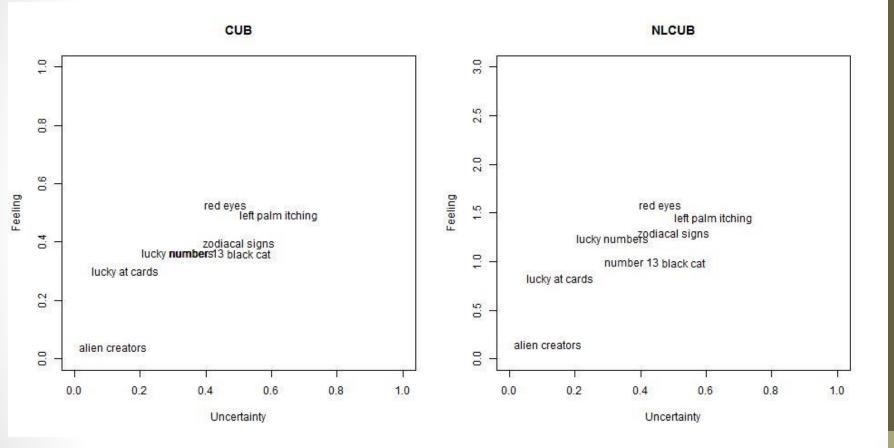
- Allow us to gain insight about the state of mind toward the rating scale
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NonLinear CUB models

- Derive from a different assumed mechanism in the Feeling approach (the Uncertainty approach is unchanged)
- Allow us to model nonlinear DPs, gaining insight about the state of mind toward the rating scale
- Include traditional CUB models as a special case

Example 1 (superstition)

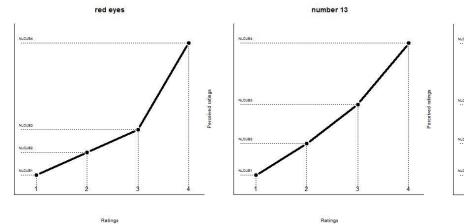




CUB models - eXamp

Example 1 (superstition)





Perceived ratings

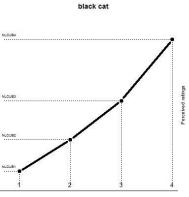
NLCUB4

NLCUB3

Perceived ratings

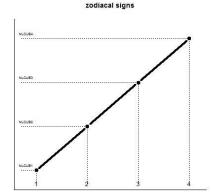
left palm itching

Ratings



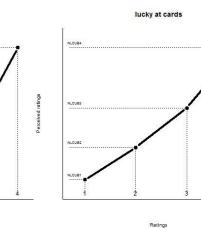
Ratings

alien creators



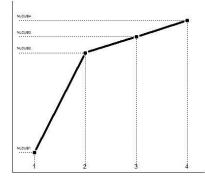
Ratings

lucky numbers



Ratings

Perceived ratings

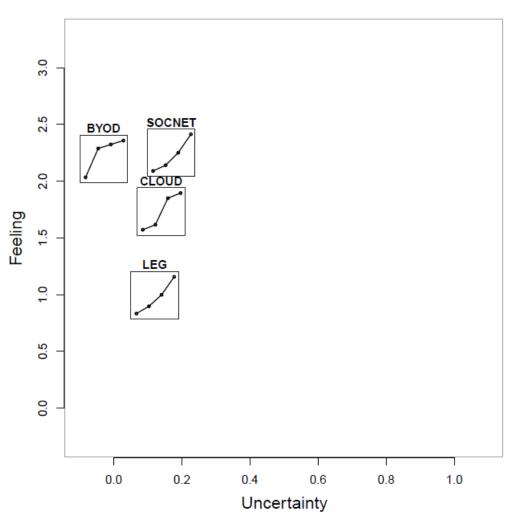


Ratings

UB models examt



Perceived risk for different technologies



CUB models - example 2





CUB models - example

- Manisera & Zuccolotto (*Pattern Recognition Letters*, 2014) have proposed a procedure to take into account the presence of "don't know" responses (DK)
- The idea is that DKs inform about the uncertainty of the respondents, so they can be introduced in the CUB framework
- DKs determine an adjustment of the uncertainty parameter

Example 3 (Standard Eurobarometer 81)

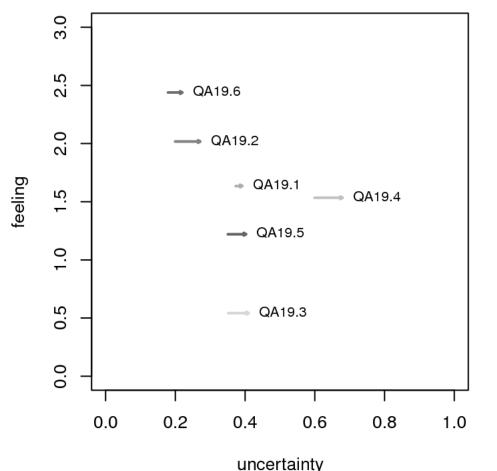


CUB models

- example

The arrows show the shift in uncertainty due to the presence of DK responses.

The arrows are coloured in a gray-level scale. The darker the colour, the higher the degree of nonlinearity of the transition plot, according to a nonlinearity index λ proposed by Manisera&Zuccolotto (QdS - Journal of Methodological and Applied Statistics, 2013)



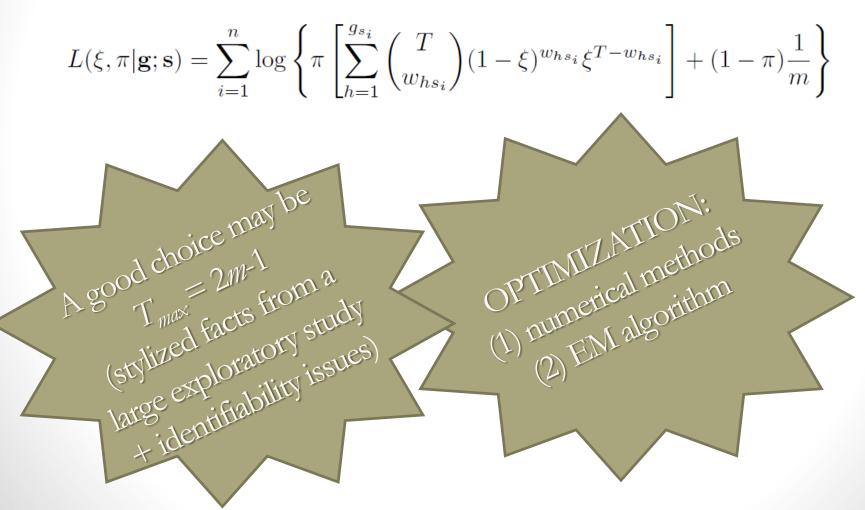
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Parameter estimation (two-steps procedure)

$$L(\xi, \pi | \mathbf{g}; \mathbf{s}) = \sum_{i=1}^{n} \log \left\{ \pi \left[\sum_{h=1}^{g_{s_i}} \binom{T}{w_{hs_i}} (1-\xi)^{w_{hs_i}} \xi^{T-w_{hs_i}} \right] + (1-\pi) \frac{1}{m} \right\}$$

Step 1: Fix a maximum value T_{max} for T, and maximize (•) with respect to ξ and π , for all the possible configurations of g_1, \dots, g_m such that $g_1 + \dots + g_m \leq T_{max} + 1$. At the end of this step, we have one NLCUB model for each configuration of g_1, \dots, g_m , along with the corresponding ML estimates of the parameters ξ and π .

Likelihood function for fixed g (step 1)



Model selection (step 2)

Step 2: Among the models defined in Step 1, select the 'best one' according to a given criterion. Let $\hat{\mathbf{g}}$ be the configuration corresponding to the 'best' model, the NLCUB model parameters are finally estimated by $\hat{\boldsymbol{\theta}} = (\hat{\xi}, \hat{\pi}, \hat{\mathbf{g}})'$, where

$$\hat{\xi}, \hat{\pi} = \arg\max_{\xi,\pi} L(\xi, \pi | \hat{\mathbf{g}}; \mathbf{s})$$

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> Maximum Likelihood Information criteria Out-of-sample predictive measures

Description

Generic code for Nonlinear CUB estimation, graphical representations, fit evaluation, data simulation

Usage

```
NLCUB(r,g = c(), m = c(), maxT = c(), paramO = c(0.5,0.5), freq.table = TRUE, method = "EM", draw.plot = TRUE, dk = c() )
```

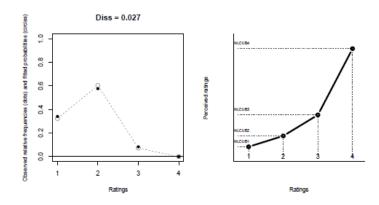
Arguments

r	a vector of observed ratings (either microdata or the m observed frequencies frequency table), see frequencies
m	frequencies - frequency table); see freq.table integer: number of categories of the response scale (active only when g is not declared)
g	a vector of the 'latent' categories assigned to each rating point;
	if g is declared, Nonlinear CUB parameters are estimated for fixed
	g, else model selection is performed in order to determine the
	optimal \mathbf{g}
maxT	integer: maximum value for T (must be $maxT > m - 1$, default is
	2m-1 (active only when g is not declared)
param0	starting values for π and ξ
freq.table	logical: if TRUE, the data in \mathbf{r} is the vector of the m observed
	frequencies (frequency table)
method	character: method to use for likelihood maximization; method="NM"
	for likelihood based - Melder-Mead maximization - method="EM"
	for likelihood based - EM algorithm
draw.plot	logical: if TRUE, two graphs are plotted: observed vs fitted frequencies
	and transition plot
dk	proportion of 'don't know' responses; if declared, in addition to the estimate of π , the estimated of π adjusted for the presence of dk responses is provided

NLCUB: R functions available!

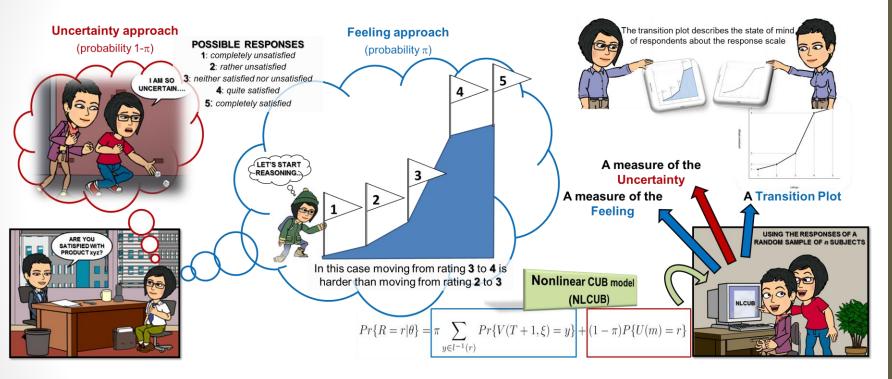
Value

pai	parameter estimate for π
csi	parameter estimate for ξ
g	optimal value for $\mathbf{g} == [g_1, \cdots, g_m]$ (if \mathbf{g} is not declared as input)
Varmat	estimated asymptotic variance-covariance matrix of the ML
	estimator for (π, ξ) for fixed g
Infmat	estimated Information matrix
Fit	m fitted frequencies, obtained according to the estimated NLCUB
	model
diss	the dissimilarity index value
transprob_mat	transition probability matrix containing $\phi_t(s)$
transprob	$m-1$ transition probabilities $\phi(s)$
uncondtransprob	unconditioned transition ϕ probability
mu	estimate of μ
NL_index	the nonlinearity index value
pai_adj	estimate of the uncertainty parameter adjusted for the presence of
	'don't know' (dk) responses



NLCUB

Summarizing...



Basic References

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Thank you



Thank you for your attention